Linear Motion and Assembly Technologies

Pneumatics

Service

R





"Rustiger vaarwater"

Wait or create?

Even voorstellen....



- Naam: Maarten Kuijpers (34)
- Bedrijf: Bosch Rexroth
- Divisie: Systems & Engineering
- Functie: Technical Project Manager.....











Hydraulics

Wave generation





Renewable Energy





Renewable Energy





Renewable Energy





Hydraulics

Jacking





Hydraulic Jacking System

- 2500 tons per leg
- 60 m/h



Gusto / Rexroth Hydraulic Jacking system



- Jacking Capacity 2500 Tonnes per Leg - Holding Capacity 5000 Tonnes per Leg - Cylinder Speed under load 60 m/h

Hydraulics

Riser Tensioning





Heave compensation





Heave Compensation - General





Hydraulics





Hydraulics





Hydraulics







Hydraulics







Hydraulics







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We also retain sole power of disposal, including all rights relating to copying, transmission and dissemination.

Passive Heave Compensation & Active Heave Compensation

Active part I

Rexroth

Bosch Group



Passive Heave Compensation & Active Heave Compensation

Active part II

Rexroth

Bosch Group



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We also retain sole power of disposal, including all rights relating to copying, transmission and dissemination.

New developments



- Active tension control for Heave Compensators
- Draghead Heave Compensation for Dredge



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Why Active Tension Control?

- Pressure variation, inertia and Friction give load variation in Passive Heave Compensation
- More accuracy in tension control required



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Measurements on Saipem 3000





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Measurements on Saipem 3000



PHC motion (200T load on seabed)



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Why Active Tension Control?

- Pressure variation, Inertia and Friction give load variation in Passive Heave Compensation
- More accuracy in tension control required
- Transition between AHC to PHC requires bypassing of AHC cylinder part transition between AHC and ATC only requires control parameters to change.

So:

Active force control instead of passive compensation.



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Why Active Tension Control?

- Pressure variation and Friction give load variation in Passive Heave Compensation
- More accuracy in tension control required
- Transition between AHC to PHC requires bypassing of AHC cylinder part
- Transition between AHC and ATC only requires control parameters to change.

Challenges

Force control is sensitive to disturbances



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Why Active Tension Control?

- Pressure variation and Friction give load variation in Passive Heave Compensation
- More accuracy in tension control required
- Transition between AHC to PHC requires abrupt bypassing of AHC cylinder part
- Transition between AHC and ATC only requires control parameters to change.

Challenges

- Force control is sensitive to disturbances
- Use MRU data Force Control



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Measurements on Saipem 3000



Direct Force control

- Uses a load cell at the fairleader
- Tests onboard Saipem 3000, show control loop can be sensitive to disturbances and is not very robust.



Measurements on Saipem 3000





AHC motion

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Cascade control

- Much less sensitive, more robust
- Also uses MRU data



Hyaraulics





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Heave compensators in Dredge Technology





Draghead control





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Active heave compensation force and position Benefits of active heave compensation with position control



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Active heave compensation force and position Benefits of active heave compensation with position control



Deepening of seabed to certain level (only removal of necessary soil)



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Active heave compensation force and position Benefits of active heave compensation with position control



Dredging layers with accuracy of 5% (poluted layers, or layers with high % rich minerals)



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"Questions?